

ON A CLASS OF SINGULAR INTEGRAL EQUATIONS WITH ROTATIONS

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ABSTRACT. The paper deals with the singular integral equation

$$a(t)\varphi(t) + b(t)[(S + M)P_\ell\varphi](t) = f(t),$$

where $a(t) = \prod_{i=1}^m (t - \alpha_i)^{r_i} s(t)$.

We will reduce the equation to the well-known Riemann boundary value problem and then describe all solution of the indicate problem in a closed form.

1. INTRODUCTION

Let Γ be a Liapunov curve on the complex plane C and X be either $L_p(\Gamma)$ ($1 < p < \infty$) or $H^\mu(\Gamma)$ ($0 < \mu < 1$). It is well-known that the singular integral operator of Cauchy's type

$$(S\varphi)(t) = \frac{1}{\pi i} \int_{\Gamma} \frac{\varphi(\tau)}{\tau - t} d\tau$$

has the property $S^2 = I$, where I is the identity operator (see [7]). The Noetherian theory of singular integral equations of Cauchy's type

$$(1) \quad a\varphi + bS\varphi + K\varphi = f$$

was started with works of Noether and Carleman in 1921, and then it was developed by many others (see [5], [6] and references there). A reason that this theory attracts a lot of attention is that there is a relation between Riemann boundary value problems of analytic functions and equations of the form (1). The operator S such as the simple-layer and double-layer potentials in Neumann's and Dirichlet's problems plays an important role in theory of boundary value problems. In [2], N. V. Mau considered the operator

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$$(2) \quad (S_{n,k}\varphi)(t) = \frac{1}{\pi i} \int_{\Gamma} \frac{\tau^{n-k-1} t^k}{\tau^n - t^n} \varphi(\tau) d\tau,$$

where n, k are nonnegative integers, $0 \leq k \leq n-1$ and proved that if $n \neq 1$ then $S_{n,k}^3 = S_{n,k}$ (note that $S_{1,0} = S$). Moreover, he also investigated equations of the form

$$(3) \quad a(t)\varphi(t) + b(t)(S_{n,k}\varphi)(t) + (N_{n,k}\varphi)(t) = f(t)$$

under the assumption $a(t) \neq 0$ on Γ . Like the singular integral equations of Cauchy's type, $(a\varphi + bS_{n,k}\varphi)$ is called a singular part and $N_{n,k}\varphi$ is called a regular part of equation (3). In this paper, we study equation (3) in the case when the function $a(t)$ has isolated zero-points on Γ . Our method is to reduce equation (3) to a system of singular integral equations of Cauchy's type whose matrix is diagonal. Theorem 4.2 indicates that the solvability of (3) depends on the solvability of the ℓ -th equation in the reduced system. Remark 4.2 at the end of this paper shows that complete equations induced by $S_{n,k}$ may be reduced to an equation of the form (3).

2. TWO LEMMAS ON MULTIPLICATIVE OPERATOR AND PROJECTIONS

Let $\Gamma = \{t : |t| = 1\}$ and $X = H^\mu(\Gamma)$ be the Hölder space on Γ . Consider the following operator in X (see [1])

$$(4) \quad (S\varphi)(t) = \frac{1}{\pi i} \int_{\Gamma} \frac{\varphi(\tau)}{\tau - t} d\tau,$$

$$(5) \quad (W\varphi)(t) = \varphi(\varepsilon_1 t),$$

$$(6) \quad (M\varphi)(t) = \frac{1}{\pi i} \int_{\Gamma} m(\tau, t) \varphi(\tau) d\tau,$$

where $\varepsilon_1 = \exp(2\pi i/n)$ (n is a positive integer) and $m(\tau, t)$ is a given function satisfying the Hölder's condition in $(\tau, t) \in \Gamma \times \Gamma$.

Denote by P_1, P_2, \dots, P_n the projections induced by the operator W . In the sequel we shall need the following identities (see [1], [2])

$$(7) \quad \left\{ \begin{array}{l} P_i = \frac{1}{n} \sum_{j=1}^n \varepsilon_i^{n-1-j} W^{j+1} \\ P_i P_j = \delta_{ij} P_j, \quad i, j = 1, 2, \dots, n \\ W^k = \sum_{j=1}^n \varepsilon_j^k P_j, \quad k = 0, 1, 2, \dots, n \\ S P_j = P_j S = S_{n,j}, \quad j = 1, 2, \dots, n, \end{array} \right.$$

where δ_{ij} is the Kronecker's symbol. For every $a \in X$ we write $(K_a \varphi)(t) = a(t)\varphi(t)$.

Lemma 2.1. *Suppose that $a \in X$ is fixed. Then for every pair (k, j) , $k, j \in \{1, 2, \dots, n\}$, there exists an element $b \in X$ such that $P_k K_a P_j = K_b P_j$ (such a function $b = b(t)$ will be denoted by $a_{kj}(t)$).*

Proof. From (5)-(7) we get

$$\begin{aligned} P_k K_a P_j &= \frac{1}{n} \sum_{\nu=1}^n \varepsilon_k^{n-1-\nu} W^{\nu+1} K_a P_j \\ &= \frac{1}{n} \sum_{\nu=1}^n \varepsilon_k^{n-1-\nu} a(\varepsilon_{\nu+1} t) W^{\nu+1} P_j \\ &= \frac{1}{n} \sum_{\nu=1}^n \varepsilon_k^{n-1-\nu} a(\varepsilon_{\nu+1} t) \sum_{\mu=1}^n \varepsilon_{\mu}^{\nu+1} P_{\mu} P_j \\ &= \left(\frac{1}{n} \sum_{\nu=1}^n \varepsilon_{\nu+1}^{j-k} a(\varepsilon_{\nu+1} t) \right) P_j = a_{kj}(t) P_j, \end{aligned}$$

where

$$(8) \quad a_{kj}(t) = \frac{1}{n} \sum_{\nu=1}^n \varepsilon_{\nu+1}^{j-k} a(\varepsilon_{\nu+1} t).$$

Putting $a_{kj}(t) = b(t)$, we obtain $b \in X$ and $P_k K_a P_j = K_b P_j$.

Lemma 2.2. *Let $a \in X$ be fixed. Then for every pair (k, j) , $k, j \in \{1, 2, \dots, n\}$, the above identity yields*

$$P_k K_{a_{kj}} = K_{a_{kj}} P_j,$$

where $a_{kj}(t)$ is defined by (8).

Proof. For any $\varphi \in X$, we have

$$\begin{aligned}
(P_k K_{a_{kj}} \varphi)(t) &= P_k a_{kj}(t) \varphi(t) = \frac{1}{n} \sum_{\nu=1}^n \varepsilon_k^{n-1-\nu} W^{\nu+1} a_{kj}(t) \varphi(t) \\
&= \left(\frac{1}{n} \sum_{\nu=1}^n \varepsilon_k^{n-1-\nu} W^{\nu+1} \right) \left(\frac{1}{n} \sum_{\mu=1}^n \varepsilon_{\mu+1}^{j-k} a(\varepsilon_{\mu+1} t) \right) \varphi(t) \\
&= \frac{1}{n} \sum_{\nu=1}^n \left[\frac{1}{n} \sum_{\mu=1}^n \varepsilon_{\mu+1}^{j-k} \varepsilon_{\nu+1}^{j-k} a(\varepsilon_{\mu+1} \varepsilon_{\nu+1} t) \right] \varepsilon_{\nu+1}^{k-j} \varepsilon_k^{n-1-\nu} W^{\nu+1} \varphi(t) \\
&= \frac{1}{n} \sum_{\nu=1}^n a_{kj}(t) \varepsilon_{\nu+1}^{k-j} \varepsilon_k^{n-1-\nu} W^{\nu+1} \varphi(t) \\
&= a_{kj}(t) \left[\frac{1}{n} \sum_{\nu=1}^n \varepsilon_j^{n-1-\nu} W^{\nu+1} \right] \varphi(t) \\
&= a_{kj}(t) (P_j \varphi)(t) \\
&= (K_{a_{kj}} P_j \varphi)(t).
\end{aligned}$$

Thus $P_k K_{a_{kj}} \equiv K_{a_{kj}} P_j$. The proof is complete.

3. REDUCING EQUATION (3) TO A SYSTEM OF SINGULAR INTEGRAL EQUATIONS

Now we consider the following equation in X

$$(9) \quad a(t)\varphi(t) + b(t)[(S + M)P_\ell \varphi](t) = f(t),$$

where $a, b, f \in X$ are given and S, M, P_ℓ ($1 \leq \ell \leq n$) are the operators defined by (4), (5), (6), (7). Suppose that the function $a(t)$ has isolated zero-points on Γ , i.e.

$$a(t) = \prod_{i=1}^m (t - \alpha_i)^{r_i} s(t),$$

where $\alpha_i \in \Gamma$, $r_i, i = 1, 2, \dots, m$, are positive integers and $s(t)$ is a non-vanishing function on Γ (*). Without loss of generality we may assume that $s(t) = 1$.

(*) The idea of this assumption was posed by Prof. Ng. V. Mau

Lemma 3.1. *Suppose that the function $m(\tau, t)$ satisfies the condition $m(\tau, t) = m(\varepsilon_1\tau, t) = m(\tau, \varepsilon_1t)$. Then $\varphi \in X$ is a solution of (9) if and only if $\{\varphi_k = P_k\varphi, k = 1, 2, \dots, n\}$ is a solution of the following system*

$$(10) \quad a^*(t)\varphi_k(t) + b_{k\ell}^*(t)(S + M)\varphi_\ell(t) = f_k^*(t), \quad k = 1, 2, \dots, n,$$

where

$$(11) \quad \begin{aligned} a^*(t) &= \prod_{j=1}^n a(\varepsilon_{j+1}t) \\ b_{k\ell}^*(t) &= \frac{1}{n} \sum_{j=1}^n \varepsilon_{j+1}^{\ell-k} b(\varepsilon_{j+1}t) \prod_{\substack{\mu \neq j \\ \mu=1}}^n a(\varepsilon_{\mu+1}t) \\ f_k^*(t) &= \frac{1}{n} \sum_{j=1}^n \varepsilon_k^{n-1-j} f(\varepsilon_{j+1}t) \prod_{\substack{\mu \neq j \\ \mu=1}}^n a(\varepsilon_{\mu+1}t). \end{aligned}$$

Proof. Since $\varphi \in X$ is the solution of (9), it follows

$$(12) \quad \begin{aligned} \prod_{\mu=1}^n a(\varepsilon_{\mu+1}t)\varphi(t) + b(t) \prod_{\substack{\mu=1 \\ \mu \neq (n-1)}}^n a(\varepsilon_{\mu+1}t)(S + M)P_\ell\varphi &= \\ &= f(t) \prod_{\substack{\mu=1 \\ \mu \neq (n-1)}}^n a(\varepsilon_{\mu+1}t). \end{aligned}$$

It is clear that $K_{a^*}P_k = P_kK_{a^*}$, ($a^*(t)$ is defined by (11)). Applying the projections $P_k, k = 1, 2, \dots, n$ to both sides of (12) and using Lemma 2.1 we obtain

$$(13) \quad \begin{aligned} a^*(t)P_k\varphi + \left[\frac{1}{n} \sum_{j=1}^n \varepsilon_{j+1}^{\ell-k} b(\varepsilon_{j+1}t) \prod_{\substack{\mu=1 \\ \mu \neq (n-1)}}^n a(\varepsilon_{\mu+1}\varepsilon_{j+1}t) \right] (S + M)P_\ell\varphi &= \\ = \frac{1}{n} \sum_{j=1}^n \varepsilon_k^{n-1-j} f(\varepsilon_{j+1}t) \prod_{\substack{\mu=1 \\ \mu \neq (n-1)}}^n a(\varepsilon_{\mu+1}\varepsilon_{j+1}t). \end{aligned}$$

It is easy to see that

$$\prod_{\substack{\mu=1 \\ \mu \neq (n-1)}}^n a(\varepsilon_{\mu+1}\varepsilon_{j+1}t) \equiv \prod_{\substack{\mu=1 \\ \mu \neq j}}^n a(\varepsilon_{\mu+1}t) \quad \text{for any } j \in \{1, 2, \dots, n\}.$$

Hence, (13) is equivalent the following system

$$a^*(t)P_k\varphi + b_{k\ell}^*(t)(S + M)P_\ell\varphi = f_k^*(t), \quad k = 1, 2, \dots, n.$$

Thus $(P_1\varphi, P_2\varphi, \dots, P_n\varphi)$ is a solution of (10).

Conversely, suppose that there exists $\varphi \in X$ such that

$$a^*(t)P_k\varphi + b_{k\ell}^*(t)(S + M)P_\ell\varphi = f_k^*(t), \quad k = 1, 2, \dots, n.$$

Summing by k ($k = 1, 2, \dots, n$) we obtain

$$(14) \quad a^*(t)\varphi(t) + \sum_{k=1}^n b_{k\ell}^*(t)(S + M)P_\ell\varphi = \sum_{k=1}^n f_k^*(t).$$

From (11) we get

$$\begin{aligned} \sum_{k=1}^n b_{k\ell}^*(t) &= \sum_{k=1}^n \frac{1}{n} \sum_{j=1}^n \varepsilon_{j+1}^{\ell-k} b(\varepsilon_{j+1}t) \prod_{\substack{\mu \neq j \\ \mu=1}}^n a(\varepsilon_{\mu+1}t) \\ &= \sum_{j=1}^n \left[\frac{1}{n} \sum_{k=1}^n \varepsilon_{j+1}^{\ell-k} \right] b(\varepsilon_{j+1}t) \prod_{\substack{\mu \neq j \\ \mu=1}}^n a(\varepsilon_{\mu+1}t) \\ (15) \quad &= \sum_{j=1}^n \delta_{j(n-1)} b(\varepsilon_{j+1}t) \prod_{\substack{\mu \neq j \\ \mu=1}}^n a(\varepsilon_{\mu+1}t) \\ &= b(t) \prod_{\substack{\mu=1 \\ \mu \neq (n-1)}}^n a(\varepsilon_{\mu+1}t). \end{aligned}$$

Similarly,

$$(16) \quad \sum_{k=1}^n f_k^*(t) = f(t) \prod_{\substack{\mu=1 \\ \mu \neq (n-1)}}^n a(\varepsilon_{\mu+1}t).$$

The identities (14), (15), (16) together give

$$\begin{aligned} \prod_{\mu=1}^n a(\varepsilon_{\mu+1}t)\varphi(t) + b(t) \prod_{\substack{\mu=1 \\ \mu \neq (n-1)}}^n a(\varepsilon_{\mu+1}t)(S + M)P_\ell\varphi &= \\ &= f(t) \prod_{\substack{\mu=1 \\ \mu \neq (n-1)}}^n a(\varepsilon_{\mu+1}t). \end{aligned}$$

This implies

$$a(t)\varphi(t) + b(t)(S + M)P_\ell\varphi = f(t).$$

The proof is complete.

Lemma 3.2. *If $(\varphi_1, \varphi_2, \dots, \varphi_n)$ is a solution of the system (10) then $(P_1\varphi_1, P_2\varphi_2, \dots, P_n\varphi_n)$ is also its solution.*

Proof. Suppose that $(\varphi_1, \varphi_2, \dots, \varphi_n)$ is a solution of (10). Applying the projections P_k to both sides of the equations (10) we have

$$(17) \quad a^*(t)P_k\varphi_k + P_k b_{k\ell}^*(t)(S + M)\varphi_\ell(t) = P_k f_k^*(t).$$

The following identities hold

$$\begin{aligned} P_k b_{k\ell}^*(t) &= \frac{1}{n} \sum_{i=1}^n \varepsilon_k^{n-1-i} W^{i+1} \frac{1}{n} \sum_{j=1}^n \varepsilon_{j+1}^{\ell-k} b(\varepsilon_{j+1}t) \prod_{\substack{\mu \neq j \\ \mu=1}}^n a(\varepsilon_{\mu+1}t) \\ &= \frac{1}{n} \sum_{i=1}^n \left[\frac{1}{n} \sum_{j=1}^n \varepsilon_{j+1}^{\ell-k} \varepsilon_{i+1}^{\ell-k} b(\varepsilon_{j+1}\varepsilon_{i+1}t) \times \right. \\ (18) \quad &\times \left. \prod_{\substack{\mu \neq j \\ \mu=1}}^n a(\varepsilon_{\mu+1}\varepsilon_{i+1}t) \right] \varepsilon_k^{n-1-i} \varepsilon_{i+1}^{k-\ell} W^{i+1} \\ &= \frac{1}{n} \sum_{i=1}^n b_{k\ell}^*(t) \varepsilon_\ell^{n-1-i} W^{i+1} = b_{k\ell}^*(t) P_\ell, \end{aligned}$$

$$\begin{aligned} P_k f_k^*(t) &= \frac{1}{n} \sum_{i=1}^n \varepsilon_k^{n-1-i} W^{i+1} \frac{1}{n} \sum_{j=1}^n \varepsilon_k^{n-1-j} f(\varepsilon_{j+1}t) \prod_{\substack{\mu \neq j \\ \mu=1}}^n a(\varepsilon_{\mu+1}t) \\ (19) \quad &= \frac{1}{n} \sum_{i=1}^n \varepsilon_k^n \left[\frac{1}{n} \sum_{j=1}^n \varepsilon_k^{n-(j+i+2)} f(\varepsilon_{j+i+2}t) \prod_{\substack{\mu \neq j \\ \mu=1}}^n a(\varepsilon_{j+i+2}t) \right] \\ &= \frac{1}{n} \sum_{i=1}^n f_k^*(t) = f_k^*(t). \end{aligned}$$

Substituting (18), (19) in (17) we obtain

$$a^*(t)P_k\varphi_k + b_{k\ell}^*(t)(S + M)P_\ell\varphi_\ell = f_k^*(t), \quad k = 1, 2, \dots, n.$$

Therefore $(P_1\varphi_1, P_2\varphi_2, \dots, P_n\varphi_n)$ is a solution of (10). The lemma is proved.

4. THE SOLVABILITY OF EQUATION (3)

Theorem 4.1. *Suppose that the function $m(\tau, t)$ satisfies the assumption of Lemma 3.1*

(i) *If $(\varphi_1, \varphi_2, \dots, \varphi_n)$ is a solution of (10), then*

$$\varphi = \sum_{i=1}^n P_i \varphi_i$$

is a solution of equation (9).

(ii) *If $\varphi \in X$ is a solution of (9) then $(P_1\varphi, P_2\varphi, \dots, P_n\varphi)$ is a solution of (10).*

Proof. (i) By Lemma 3.2, $(P_1\varphi_1, P_2\varphi_2, \dots, P_n\varphi_n)$ is also a solution of (10). We put

$$\varphi = \sum_{i=1}^n P_i \varphi_i.$$

It is clear that $P_k\varphi = P_k\varphi_k$. It means that $(P_1\varphi, P_2\varphi, \dots, P_n\varphi)$ is a solution of (10). Hence, we have

$$a^*(t)P_k\varphi + b_{k\ell}^*(t)(S + M)P_\ell\varphi = f_k^*(t), \quad k = 1, 2, \dots, n.$$

Summing by k of both sides of the last equations and using (15), (16) we obtain

$$a^*(t)\varphi(t) + b(t) \prod_{\substack{\mu=1 \\ \mu \neq (n-1)}}^n a(\varepsilon_{\mu+1}t)(S + M)P_\ell\varphi = f(t) \prod_{\substack{\mu=1 \\ \mu \neq (n-1)}}^n a(\varepsilon_{\mu+1}t).$$

Thus

$$a(t)\varphi(t) + b(t)(S + M)P_\ell\varphi = f(t).$$

(ii) The conclusion follows immediately from Lemma 3.1. The proof is complete.

Remark 4.1. Theorem 4.1 shows that it is sufficient to solve the system (10) in the given space $X = H^\mu(\Gamma)$.

We set

$$\Omega = \{\varepsilon_{\mu+1}^{-1}\alpha_i, \quad \mu = 1, 2, \dots, n; \quad i = 1, 2, \dots, m\}$$

$$\{g(t)\}_{(k,t_0)} = \frac{d^k g(t)}{dt^k} \Big|_{t=t_0}.$$

Theorem 4.2. *Suppose that the function $m(\tau, t)$ satisfies the assumption of Lemma 3.1. Then the equation (9) has a solution in X if and only if the equation*

$$(20) \quad a^*(t)\varphi(t) + b_{\ell\ell}^*(t)(S + M)\varphi = f_\ell^*(t)$$

has a solution $\varphi_0(t)$ satisfying the following conditions

$$(21) \quad \{f_k^*(t) - b_{k\ell}^*(t)(S + M)\varphi_0(t)\}_{(k,t_i)} = 0,$$

where $t_i \in \Omega$, $k = 0, 1, 2, \dots, r_i$, $i = 1, 2, \dots, m$.

Proof. Since $\varphi \in X$ is a solution of (9), it follows from Lemma 2.1 that the system (10) has a solution $(P_1\varphi, P_2\varphi, \dots, P_n\varphi)$. It means that $P_\ell\varphi$ is the solution of the ℓ -th equation of (10)

$$a^*(t)P_\ell\varphi(t) + b_{\ell\ell}^*(t)(S + M)P_\ell\varphi = f_\ell^*(t),$$

i.e. the equation (20) has solutions. Let $\varphi_0(t)$ be a certain solution of (20). Since (10) has solutions it follows that for every $k = 1, 2, \dots, n$, $\varphi_k(t)$ is a solution of the equation

$$(22) \quad a^*(t)\varphi_k(t) = f_k^*(t) - b_{k\ell}^*(t)(S + M)\varphi_0(t).$$

The left side of (22) is a function having zero of order r_i at $t_i = \varepsilon_{\mu+1}^{-1}\alpha_i \in \Omega$. Hence, the condition (21) is necessary. Conversely, if $\varphi_0(t)$ is a finite solution of (20) and (21) holds, then it is easy to see that (10) has a solution $(\varphi_1, \varphi_2, \dots, \varphi_n)$, where $\varphi_i \in X$. Theorem 4.1 follows that

$$\varphi = \sum_{i=1}^n P_i\varphi_i$$

is the solution of (9). The proof is complete.

We set

$$D^+ = \{z \in C : |z| < 1\}$$

$$D^- = \{z \in C : |z| > 1\}.$$

Denote by $H^+(D^+)$, $H^-(D^-)$ the sets of all analytic functions in D^+ , D^- respectively.

Corollary. *Suppose that the function*

$$M(\tau, t) = \frac{b_{\ell\ell}^*(t)}{a^*(t) + b_{\ell\ell}^*(t)} m(\tau, t)$$

admits an analytic continuation on D^+ with each variable (τ, t) and satisfies $M(\tau, t) = M(\varepsilon_1\tau, t) = M(\tau, \varepsilon_1t)$. Then the equation (9) is solvable in a closed form.

Proof. Consider the ℓ -th equation of (10)

$$(23) \quad a^*(t)\varphi_\ell(t) + b_{\ell\ell}^*(t)(S\varphi_\ell)(t) + b_{\ell\ell}^*(t)(M\varphi_\ell)(t) = f_\ell^*(t).$$

Put

$$\Phi_\ell(z) = \frac{1}{\pi i} \int_{\Gamma} \frac{\varphi_\ell(\tau)}{\tau - z} d\tau, \quad z \in C \setminus \Gamma.$$

According to Sokhotski-Plemelij formula (see [5]), equation (23) is reduced to the following boundary value problem

$$(24) \quad \Phi_\ell^+(t) - \frac{b_{\ell\ell}^*(t)}{a^*(t) + b_{\ell\ell}^*(t)} M\Phi_\ell^-(t) = \frac{a^*(t) - b_{\ell\ell}^*(t)}{a^*(t) + b_{\ell\ell}^*(t)} \Phi_\ell^-(t) + \frac{f_\ell^*(t)}{a^*(t) + b_{\ell\ell}^*(t)}.$$

From Lemma 2 in [5] (p.186) and the assumption for $M(\tau, t)$, it follows that (24) is the Riemann boundary value problem for analytic functions. Denote by $(\Psi_\ell^+(z), \Psi_\ell^-(z))$ a solution of (24). We have

$$\Phi_\ell^-(t) = \Psi_\ell^-(t)$$

and

$$\Phi_\ell^+(t) - \frac{b_{\ell\ell}^*(t)}{a^*(t) + b_{\ell\ell}^*(t)} (M\Phi_\ell^-(t)) = \Psi_\ell^+(t).$$

Hence, using Sokhotski-Plemelij formula, the solution of (24) is of the form

$$(25) \quad \varphi_\ell(t) = \Phi_\ell^+(t) - \Phi_\ell^-(t) = \Psi_\ell^+ + \frac{b_{\ell\ell}^*(t)}{a^*(t) + b_{\ell\ell}^*(t)} (M\Psi_\ell^-(t)) - \Psi_\ell^-(t).$$

Thus, from Theorems 4.1 and 4.2 we conclude that

(i) If neither equation (24) has solutions nor solutions $\varphi_\ell(t)$ of the form (25) do satisfy condition (21), then equation (9) has no solutions.

(ii) If there exists $\varphi_\ell(t)$ of the form (25) satisfying conditions (21), then equation (9) is solvable in a closed form. Solutions of (9) are given by the following formula

$$\varphi(t) = \sum_{k=1}^n (P_k \varphi_k)(t),$$

where $\varphi_\ell(t)$ is defined by (25) and $\varphi_k(t)$, $1 \leq k \neq \ell \leq n$, are defined clearly from system (10).

Remark 4.2. The complete singular integral equation induced by $S_{n,j}$ is of the form

$$(26) \quad a(t)\varphi(t) + b(t)(S_{n,j}\varphi)(t) + c(t)(S_{n,j}^2\varphi)(t) = f(t).$$

From (7) it follows $S_{n,j}^2 = P_{n,j}$. Thus (26) is of the form (9).

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