

THE FUNDAMENTAL GROUP OF COMPLEX HYPERPLANES ARRANGEMENTS

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1. Introduction

Let V be a complex vector space of finite dimension. An arrangement is a finite family of affine hyperplanes in V . Given an arrangement $\mathcal{A} = \{H\}$. Let's consider the complement

$$M = V - N,$$

where $N = \bigcup_{H \in \mathcal{A}} H$. The purpose of this paper is to give a presentation for the fundamental group $\pi_1(M)$ of this complement. By standard arguments using Lefschetz Theorem (see [3]) we can always reduce to the case when V is a complex vector space of dimension 2. So, from now on we consider only the case when $\mathcal{A} = \{H_i | i = 1, \dots, n\}$ is an arrangement of complex lines in $V = \mathbb{C}^2$.

Such a presentation has been given in [2], [7], [9] for the case when \mathcal{A} is the complexification of a real arrangement. In [1], W. Arvola has considered the case of an arbitrary complex arrangement and has given a presentation for the fundamental group of its complement using a certain planar graph defined by himself. In this paper we will follow a quite different method. Our computation is based on the so-called labyrinth of an arrangement of complex lines, which dues to L. Rudolph [8]. This construction of L. Rudolph has been used also by Y. Orevkov [5], in proving the Zariski's conjecture of the abelity of the fundamental group of the complement of a curve with nodes.

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2. Labyrinth

Suppose that \mathbb{C}^2 is given with the coordinates (x, y) . Each hyperplane H_i of \mathcal{A} can be then defined by an equation $y = \alpha_i(x)$, where α_i is a certain linear function. We denote by R_i and I_i the real and the imaginary parts of $\alpha_i(x)$ respectively. Then the subset $L_{i,j}$ of the x -axis \mathbb{C}_x , defined by

$$L_{i,j} = \{x \in \mathbb{C}_x \mid R_i = R_j\},$$

is a (*real*) line on the (*real*) plane \mathbb{C}_x . The union of these lines

$$\mathcal{L}(\mathcal{A}) = \bigcup_{1 \leq i < j \leq n} L_{i,j}$$

will be called the labyrinth of the arrangement \mathcal{A} . For each line $L \in \mathcal{L}(\mathcal{A})$ there may be $i_1, \dots, i_k, 1 \leq i_1 < i_2 < \dots < i_k \leq n$, such that L is defined by $R_{i_s} = R_{i_t}, 1 \leq s < t \leq k$. The number $k - 1$ will be called the multiplicity of L .

REMARK 2.1. After a suitable change of coordinates we can always assume that the multiplicity of any line $L \in \mathcal{L}(\mathcal{A})$ is 1.

Clearly, each line $L_{i,j}$ divides \mathbb{C}_x into two parts $L_{i,j}^+ = \{x \in \mathbb{C}_x \mid R_i(x) < R_j(x)\}$ and $L_{i,j}^- = \{x \in \mathbb{C}_x \mid R_i(x) > R_j(x)\}$. Each component U of $\mathbb{C}_x - \mathcal{L}(\mathcal{A})$ can be defined by $R_{s(1)} < \dots < R_{s(n)}$ for a certain permutation s of the set $\{1, \dots, n\}$.

Now we describe the group $\pi_1(M)$ in terms of the labyrinth $\mathcal{L}(\mathcal{A})$. We choose the base point to be the infinite point on the positive half of the axis $Im y$. Let U be a connected component of $\mathbb{C}_x - \mathcal{L}(\mathcal{A})$. Choose an arbitrary point $x_0 \in U$. Set $\tilde{\mathbb{C}}_{x_0} = \{(x, y) \in \mathbb{C}^2 \mid x = x_0\}$. It is the standard fiber of the projection $\pi : \mathbb{C} \rightarrow \mathbb{C}_x$. Then $\tilde{\mathbb{C}}_{x_0} - N$ is a punctured plane with n points removed. Suppose that these points Q_1, \dots, Q_n are ordered in such a way that their real parts are increasing. For $1 \leq i \leq n$ let γ_i denote the path on $\tilde{\mathbb{C}}_{x_0}$ which comes from infinity straight down to a point, a little higher than Q_i , then goes counterclockwise along a small circle around Q_i and goes back to the infinity by the same line as illustrated in Figure 1.

The fundamental group of $\tilde{\mathbb{C}}_{x_0} - N$ is then the free group with generators being the homotopy classes of these loops $\gamma_i, i = 1, \dots, n$. Identifying these

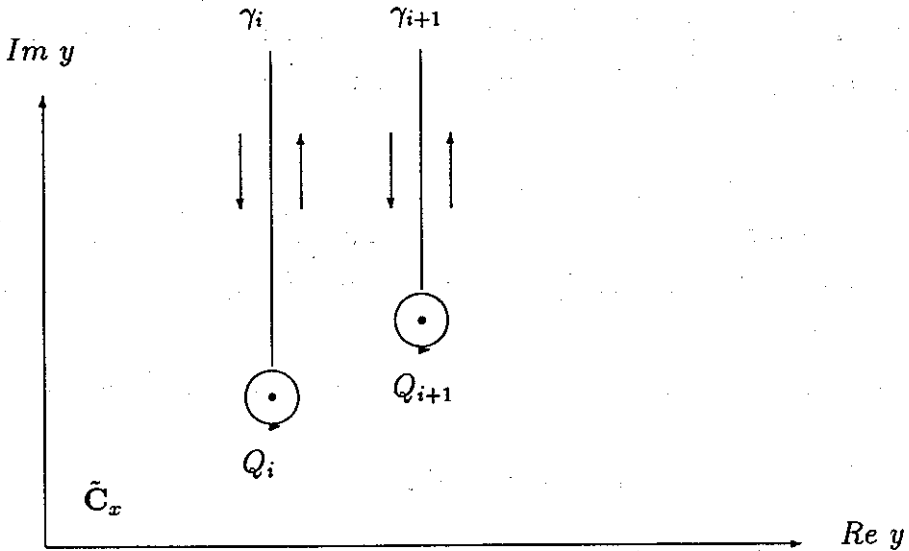


Figure 1

classes with their images in the group $\pi_1(\mathbb{C}^2 - N)$, it is easy to show (see e.g [10] that for a chosen component U , the homotopy classes of $\gamma_1, \dots, \gamma_n$, which will be denoted by the same notation $\gamma_1, \dots, \gamma_n$, generate the group $\pi_1(M)$. Obviously, the ordered set $\{\gamma_1, \dots, \gamma_n\}$ does not depend on the choice of x_0 in U . Therefore, from now on we will denote these paths by $\gamma_1(U), \dots, \gamma_n(U)$ and the set $\{\gamma_1(U), \dots, \gamma_n(U)\}$ by $\Gamma(U)$.

In order to determine defining relations of $\pi_1(M)$ we consider multiple points of the arrangement \mathcal{A} . By definition, a multiple point is the intersection of two or more hyperplanes of \mathcal{A} . After a suitable change of coordinates we can assume that multiple points are distinct by their x -coordinates. In other words, the images of multiple points on \mathbb{C}_x are pairwise distinct. Denote these images

by $\bar{P}_1, \dots, \bar{P}_m$. Take m simple loops η_1, \dots, η_m based at x_0 on the x -axis C_x , which surround $\bar{P}_1, \dots, \bar{P}_m$ respectively and exclusively and do not surround any point of $C_x \cap N$. Moving the fiber \tilde{C}_{x_0} along the loop η_j we will get a deformation of $\tilde{C}_{x_0} - N$ into itself. This deformation sends each loop γ_i to a new loop in $\tilde{C}_{x_0} - N$. The homotopy class of the later can be expressed as a word $w_{i,j}$ of $\gamma_1, \dots, \gamma_n$. Then among generators of $\pi_1(C^2 - N)$ we have the relation

$$\gamma_i = w_{i,j}(\gamma_1, \dots, \gamma_n). \quad (R_{i,j})$$

The classical method (see [10], [4]) shows that the group $\pi_1(C^2 - N)$ has a presentation with generators $\{\gamma_1, \dots, \gamma_n\}$ and defining relations $R_{i,j} : 1 \leq i \leq n, 1 \leq j \leq m$.

In the rest of this paper we will write out $R_{i,j}$ from the labyrinth $\mathcal{L}(\mathcal{A})$.

3. Determining relations

Let \mathcal{A} be an arrangement in $V = C^2$ and $\mathcal{L}(\mathcal{A})$ its labyrinth. As in the previous section, for each component U of $C_x - \mathcal{L}(\mathcal{A})$ we associate an ordered set $\Gamma(U) = \{\gamma_1(U), \dots, \gamma_n(U)\}$ of paths on the standard fiber of the projection π over a certain point $x_0 \in U$.

Suppose that U and U' are two adjacent components of $C_x - \mathcal{L}(\mathcal{A})$, i.e. the affine support of the intersection $U \cap U'$ is a line $L \in \mathcal{L}(\mathcal{A})$. First we want to know how the set $\Gamma(U)$ is changed when the point x_0 moves from U to U' . Let $\Gamma(U) = \{\gamma_1(U), \dots, \gamma_n(U)\}$. By means of Remark 2.1 we can assume that the line $L \in \mathcal{L}(\mathcal{A})$ is defined by real parts of two hyperplanes, which determine $\gamma_i(U)$ and $\gamma_{i+1}(U)$, for some $1 \leq i \leq n-1$. Without loss of generality, we may also assume that these hyperplanes are H_i and H_{i+1} , i.e. L is defined by the equation $R_i = R_{i+1}$. Suppose that $U \subset L^+$ and $U' \subset L^-$. We have then $\Gamma(U') = \{\gamma_1(U'), \dots, \gamma_n(U')\}$, where

$$\gamma_j(U') = \gamma_j(U) \text{ with } j < i \text{ and } j > i + 1.$$

In order to relate $\gamma_i(U), \gamma_{i+1}(U)$ and $\gamma_i(U'), \gamma_{i+1}(U')$ we consider the (real) line L' on C_x , defined by the equation $I_i = I_{i+1}$. Also, the line L' divides C_x into

two parts $L'^+ = \{c \in C_x; I_i(c) < I_{i+1}(c)\}$ and $L'^- = \{c \in C_x; I_i(c) > I_{i+1}(c)\}$. There are two cases.

1) x_0 moves from U to U' along a path lying in L'^+ . In this case we have

$$(A) \begin{cases} \gamma_i(U') = \gamma_i(U)^{-1} \cdot \gamma_{i+1}(U) \cdot \gamma_i(U), \\ \gamma_{i+1}(U') = \gamma_i(U). \end{cases}$$

2) x_0 moves from U to U' along a path lying in L'^- . In this case we have

$$(B) \begin{cases} \gamma_i(U') = \gamma_{i+1}(U), \\ \gamma_{i+1}(U') = \gamma_{i+1}(U) \cdot \gamma_i(U) \cdot \gamma_{i+1}(U)^{-1} \end{cases}$$

The above relations are consequences of the definition of $\gamma_i(U)$ and of the following lemma.

LEMMA 3.1(see [6]). Consider the three loops in $\mathbb{R}^2 - \{2 \text{ points}\}$, which are depicted as in the Figure 2. Among these we have two relations

$$\gamma = \beta^{-1} \cdot \alpha \cdot \beta \text{ and } \alpha = \beta \cdot \gamma \cdot \beta^{-1}$$

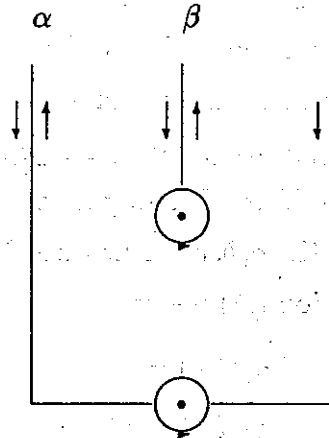


Figure 2

Next we want to know what relation will be given locally when x_0 moves around the image of a multiple point. Suppose that \bar{P} is the image of a multiple

point P ; U is a component of $C_x - \mathcal{L}(\mathcal{A})$ which is incident to \bar{P} ; i.e. U has \bar{P} on its boundary and $\Gamma(U) = \{\gamma_1(U), \dots, \gamma_n(U)\}$. Suppose that P is the intersection of the hyperplanes which define $\gamma_i(U), \gamma_{i+1}(U), \dots, \gamma_j(U)$ for certain $1 \leq i < j \leq n$. Without loss of generality we may assume that these hyperplanes are H_i, H_{i+1}, \dots, H_j . Then we have

LEMMA 3.2. Consider the fundamental group $\pi_1(M)$ with generators $\gamma_1(U), \dots, \gamma_n(U)$. We have

$$\gamma_j(U)\gamma_{j-1}(U)\dots\gamma_i(U) = \gamma_{c(j)}(U)\gamma_{c(j-1)}(U)\dots\gamma_{c(i)}(U),$$

where c is any cyclic permutation of $\{j, j-1, \dots, i\}$.

PROOF. By moving $x_0 \in U$ around \bar{P} the paths $\gamma_1(U), \dots, \gamma_n(U)$ are deformed into paths $\alpha_1(U), \dots, \alpha_n(U)$. Denote the homotopy classes of these paths by the same notation $\alpha_1(U), \dots, \alpha_n(U)$. Obviously, we have

$$\alpha_l(U) = \gamma_l(U) \text{ for } l < i \text{ and } l > j.$$

We will try to relate $\gamma_i(U), \dots, \gamma_j(U)$ to $\gamma_i(U), \dots, \gamma_j(U)$. For the sake of simplicity we consider the case when $i = 1$ and $j = 3$, as illustrated in Figure 3. The general case is quite similar.

Let U be contained in the domain of C_x defined by $R_1 < R_2 < R_3$ and other components, which incident to \bar{P} , in corresponding domains as determined in Figure 3. Denote $\gamma_1(U), \gamma_2(U)$ and $\gamma_3(U)$ simply by a, b and c respectively. Suppose that x_0 moves from U to U_1 along a path lying in $L_{1,2}^+$. After x_0 has moved from U to U_1 , the paths a, b, c are deformed into $\gamma_1(U_1), \gamma_2(U_1), \gamma_3(U_1)$, respectively. Using the relation (A) we have

$$\gamma_1(U_1) = a^{-1}ba$$

$$\gamma_2(U_1) = a$$

$$\gamma_3(U_1) = c.$$

Suppose that when coming back to the component U the paths a, b, c are deformed into the paths α, β, γ , respectively. Continuing the above procedure, the homotopy classes of these new paths, denoted by the same notations α, β, γ , can be expressed as

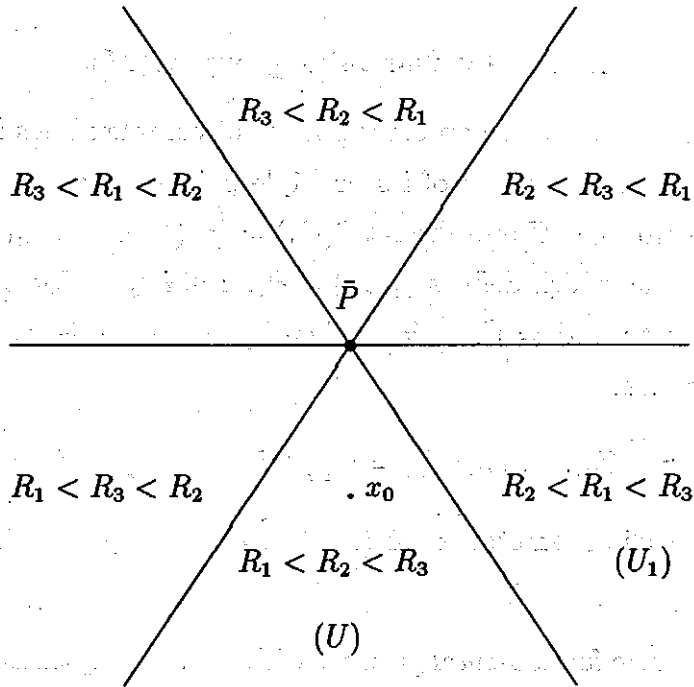


Figure 3

$$\alpha = a^{-1}b^{-1}c^{-1}acba$$

$$\beta = a^{-1}b^{-1}c^{-1}bcba$$

$$\gamma = a^{-1}b^{-1}cba$$

Therefore, in the group $\pi_1(M)$ we have the following relations

$$a = a^{-1}b^{-1}c^{-1}acba$$

$$b = a^{-1}b^{-1}c^{-1}bcba$$

$$c = a^{-1}b^{-1}cba$$

From these relations we easily get

$$cba = bac = acb.$$

The proof is complete.

4. The fundamental group $\pi_1(M)$.

Let $\mathcal{A} = \{H_1, \dots, H_n\}$ be an arrangement of complex lines in \mathbb{C}^2 with the complement M and the set \mathcal{M} of its multiple points. Fix a component U_0 of $\mathbb{C}_x - \mathcal{L}(\mathcal{A})$, a point $x_0 \in U_0$ and the set $\Gamma(U_0) = \{\gamma_1(U_0), \dots, \gamma_n(U_0)\}$. Suppose that the hyperplane which defines $\gamma_i(U_0)$ is H_i , $1 \leq i \leq n$. For a multiple point $P \in \mathcal{M}$ suppose that $P = \bigcap_{j=1}^s H_{i_j}$. Then by $R(P)$ we denote the set of all relations of the form

$$\gamma_{i_s}(U_0) \dots \gamma_{i_1}(U_0) = \gamma_{i_{c(s)}}(U_0) \dots \gamma_{i_{c(1)}}(U_0),$$

where c is any cyclic permutation of $\{s, \dots, 1\}$. Now we state the main result of this paper.

THEOREM 4.1. *The fundamental group $\pi_1(M)$ of the complement of the arrangement \mathcal{A} has a presentation with generators $\gamma_1(U_0), \dots, \gamma_n(U_0)$ and defining relations $R(P)$, $P \in \mathcal{M}$.*

PROOF. Consider a multiple point $P = \bigcap_{j=1}^s H_{i_j}$ in \mathcal{M} . Suppose that the component U_0 is defined by $R_1 < \dots < R_{i_1} < \dots < R_{i_2} < \dots < R_{i_s} < \dots < R_n$. Without loss of generality we can assume that $i_1 = 1$ and $i_s = n$. Also, for the sake of simplicity we can assume that $s = 3$. Let fix a component U_P of $\mathbb{C}_x - \mathcal{L}(\mathcal{A})$, which is incident to the image \bar{P} on \mathbb{C}_x of P . Suppose that U_P is defined by $R_2 < R_3 < \dots < R_{j-1} < R_{j+1} < \dots < R_{n-1} < R_1 < R_j < R_n$.

Now let γ be the path going from $x_0 \in U_0$ to a point $x_P \in U_P$ defined as follows. It goes from one component to another component of $\mathbb{C}_x - \mathcal{L}(\mathcal{A})$, step by step, according to the following order

$$R_1 < R_2 < R_3 < \dots < R_{j-1} < R_j < R_{j+1} < \dots < R_{n-2} < R_{n-1} < R_n$$

$$R_1 < R_2 < R_3 < \dots < R_{j-1} < R_{j+1} < R_j < R_{j+2} < \dots < R_{n-1} < R_n$$

$$R_1 < R_2 < R_3 < \dots < R_{j-1} < R_{j+1} < R_{j+2} < \dots < R_{n-1} < R_j < R_n$$

$$R_2 < R_1 < R_3 < \dots < R_{j-1} < R_{j+1} < R_{j+2} < \dots < R_{n-1} < R_j < R_n$$

...

$$R_2 < R_3 < \dots < R_{j-1} < R_{j+1} < R_{j+2} < \dots < R_{n-1} < R_1 < R_j < R_n.$$

In each step, when γ crosses a line $L \in \mathcal{L}(\mathcal{A})$, we can choose γ so that it lies in the domain L'^+ . We can then use the relations (A) to determine $\Gamma(U)$.

By moving x_0 along the path γ to $x_P \in U_P$, then surrounding it counterclockwise around \bar{P} and moving it back to x_0 by the same path γ we obtain the relations of the group $\pi_1(M)$.

First, when x_0 moves to x_P along γ , the paths $\gamma_1(U_0), \dots, \gamma_n(U_0)$ are deformed into paths $\gamma_1(U_P), \dots, \gamma_n(U_P)$ and we have

$$\gamma_i(U_P) = \gamma_1(U_0)^{-1} \gamma_{i+1}(U_0) \gamma_1(U_0) \text{ for } i < j - 1$$

$$\gamma_i(U_P) = \gamma_1(U_0)^{-1} \gamma_j(U_0)^{-1} \gamma_{i+2}(U_0) \gamma_j(U_0) \gamma_1(U_0) \text{ for } j - 1 \leq i < n - 2$$

$$\gamma_{n-2}(U_P) = \gamma_1(U_0)$$

$$\gamma_{n-1}(U_P) = \gamma_j(U_0)$$

$$\gamma_n(U_P) = \gamma_n(U_0).$$

Suppose that after x_P has surrounded counterclockwise the multiple point \bar{P} , the paths $\gamma_i(U_P)$ are deformed into $\alpha_i(U_P)$. We have

$$\alpha_i(U_P) = \gamma_i(U_P) \text{ for } i \leq n - 3$$

$$\alpha_{n-2}(U_P) = w_1$$

$$\alpha_{n-1}(U_P) = w_2$$

$$\alpha_n(U_P) = w_3,$$

for certain words w_1, w_2, w_3 of $\gamma_1(U_0), \gamma_j(U_0), \gamma_n(U_0)$.

Now moving x_P by the same path γ back to x_0 , the paths $\alpha_i(U_P)$, $1 \leq i \leq n$, are deformed into $\alpha_i(U_0)$, $1 \leq i \leq n$, respectively. Remind that this time we

have to use (B) to relate $\alpha_i(U_0)$ and $\alpha_i(U_P)$. We have

$$\alpha_i(U_0) = w_1 \gamma_1(U_0)^{-1} \gamma_i(U_0) \gamma_1(U_0) w_1^{-1} \text{ for } 1 < i < j$$

$$\alpha_i(U_0) = w_2 w_1 \gamma_1(U_0)^{-1} \gamma_j(U_0)^{-1} \gamma_i(U_0) \gamma_j(U_0) \gamma_1(U_0) w_1^{-1} w_2^{-1} \text{ for } j < i < n$$

$$\alpha_1(U_0) = w_1$$

$$\alpha_j(U_0) = w_2$$

$$\alpha_n(U_0) = w_3.$$

Therefore, among generators $\gamma_1(U_0), \dots, \gamma_n(U_0)$ we have following relations

$$\gamma_i(U_0) = w_1 \gamma_1(U_0)^{-1} \gamma_i(U_0) \gamma_1(U_0) w_1^{-1} \text{ for } 1 < i < j$$

$$\gamma_i(U_0) = w_2 w_1 \gamma_1(U_0)^{-1} \gamma_j(U_0)^{-1} \gamma_i(U_0) \gamma_j(U_0) \gamma_1(U_0) w_1^{-1} w_2^{-1} \text{ for } j < i < n$$

$$\gamma_1(U_0) = w_1$$

$$\gamma_j(U_0) = w_2$$

$$\gamma_n(U_0) = w_3.$$

Using the last three rows we substitute w_1, w_2, w_3 in the first two rows and get trivial relations. As a consequence of Lemma 3.1, from last the three rows we obtain the required relations $R(P)$. Now an application of Van Kampen's Theorem (see [4]) completes the proof of the theorem.

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